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CLASSIFICATION

S-E-C-R-E-T

REPORT

50X1-HUM

### CENTRAL INTELLIGENCE AGENCY INFORMATION FROM FOREIGN DOCUMENTS OR RADIO BROADCASTS

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SECRET

COUNTRY

USSR

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Russian

SUPPLEMENT REPORT NO.

THIS IS UNEVALUATED INFORMATION

SOURCE

Vestnik Mashinostroyeniya, No 5, May 1951.

#### DRAGLINE POWER SYSTEM COORDINATES HOIST, DRAG MOTORS

The electrical apparatus in the ESh 14/65 walking dragline has a motorgenerator set, hoist, drag, and swing motors, pumping unit for operation of the hydraulic walking mechanisms, amplidyne booster set, and their control mechanisms.

The motor-generator set consists of six self-ventilating machines mounted on a single frame. Single-unit direct-current generators with amplidyne control feed the current for the main drive motors. The high-voltage circuits and the current collectors are installed in a special compartment at the center of the turning platform.

The coordination of the operation of the hoist and drag motors is particularly important. As the load on the drag motor increases radically, (when the bucket goes too deeply into the ground) a relay current goes into operation, and the current is increased in the hoist motor, which then automatically starts to raise the bucket out of the ground.

It is considered feasible to rig the ESh 14/65 with buckets of 10, 18, and 22-cubic-m er capacity, and booms of 50, 60, and 75-meter length, keeping the basic specifications of the machine the same.

#### Specifications

	14
Bucket capacity (cu m)	65
Length of boom (m) Estimated rate in digging earth of No 4 category and Estimated rate in digging earth of No 4 category and	
depositing it in a pile after swinging	1.1
a 100 degrees (CVC   eS/MIN)	***
Average pressure exerted on ground through support of the	0.8
	1.27
Average pressure exerted on ground by shoes (kg/cu cm)  Distance travelled in complete walking cycle (m)	2.
Distance travelled in complete warming system. Treversing speed (km/hr)	0.18
Traversing spect (im/it)	

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## Specifications

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Maximum angles of ascent and descent along which machine	10.
monovier (degrees)	87.
Maximum drag force exerted (tons)  Second of drag cable, motor operating at 80 percent	2.1
of maximum moment (m/sec)	70.
Maximum lifting force (tons)  Speed of hoist cable, motor operating at 80 percent	2.4
a	20-30
Angle of inclination of boom (regrees)	1,150.
Weight of dragline (tons)	19.8
Dimensions (m):	
Length of cab	11.2
Width of cab	11.5
Height of cab roof above earth	24.6
Height of superstructure above grand	19.6
Walking mechanism tread	16.3
Tength of walking shoes	2.5
useth of walking shoes	14.0
Diameter of supporting base	
Power of main electric motor, (kw):	2 x 540
Hoist	2 x 540
	2 x 250
Drag	2 x 260
Swing Walking mecha isms	6,000
Voltage of feeder current (kw) [sic]	0,000
Voltage of Teeder Current (/ L'/	

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